

#### **ASCON** spa

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# mod. IO-CB/DI-16LV-00

M.U. IO-CB/DI-16LV-1/04.10 Cod. J30-658-1ADI-16LV E

# User manual

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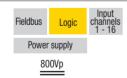
# **APPLICABLE STANDARDS**

The DI-16LV module is suited for the CiA DS301 protocol [1] and implements the CiA DS401 standard Device Profile [2].

# Characteristics Technical data Number of channels 16 Polarity (EN 61131-2 type 2) Sink (PNP) UL (state 0) -3...+11/5 Vdc UT (transition) 5....11 Vdc UH (state 1) 11... 30 Vdc Input impedance 5 kΩ ON/OFF delay 5 ms Max. monostable time 65 s

General									
3 way isolation	Channel to Channel	No							
o may loolation	Channel to Logic	800 Vp							
	Logic to Serial Bus	800 Vp							
	Power Supply to Logic	800 Vp							
Power supply	24 Vdc; -15+25%								
Power consuption	3 W								
Overvoltage protection	40 Vdc								
Dimensions	L: 76; H: 110; W: 65								
Weight	220 g								
Safety regulations	Isolation class II (50Vrms)	,							
EN61010-1	Installation cathegory II,								
	Pollution degree 2								
CE marking	EN61131-2								

# 3 way isolation diagram



Environment										
	Operating	Storage								
Temperature	-10+65°C	-40+85°C								
Relative	595% non condensing	595% non condensing								
Humidity	Appropriate measures must	For a short period, slight								
	be taken against humidity	condensation may appear								
	>85%	on the housing								
Mounting	Vertical, free air									
Protection	IP20									
Vibrations	1057Hz 0.0375mm									
(3 axes)	57150Hz 0.5g									
Shock (3 axes)	15g, 11ms half sine									

# CANopen I/O module 16 Isolated Digital Inputs mod. IO-CB/DI-16LV-00



# 16 optoisolated digital inputs with special functions

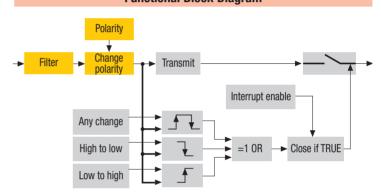
- Latched inputs
- Monostable inputs
- Edge detect and interrupt



# **↑** WARNING

The product described in this manual should only be installed, operated and maintained by qualified application programmers and software engineers who are familiar with automation safety concepts and applicable national standards.

# **Functional Block Diagram**

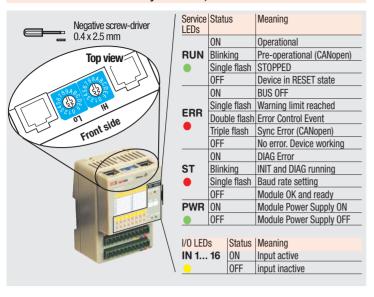


PDOs used by the module										
TPD0	Properties	Mapped objects	Index	Sub-index						
TPDO 1	COBID: 180h+ NodelD	Read digital input (1-8)	6000h	01h						
	Transmission Type: FFh	Read digital input (9-16)	6000h	02h						
TPDO 2	COBID: 280h+ NodelD	Read Input Latch 1-8	2011h	01h						
	Transmission Type: FFh	Read Input Latch 9-16	2011h	02h						
		Read Input Wait 1-8	2012h	01h						
		Read Input Wait 9-16	2012h	02h						

**Note:** The transmission type is configurable; FFh is the default value.

#### **Hardware Set-up**

#### Hexadecimal rotary switches, service and I/O LEDs



## Bit Rate and Node ID configuration

## Bit rate

Lo switch	Baud rate kbps	Bus length m
1	20	2500
2	50	1000
3	100	500
4	125	500
5	250	250
6	500	100
7	800	50
8	1000	25

#### **Node ID**

Lo switch	Valid ID Node
1	01h (address 1)
2	02h (address 2)
$\overline{\Psi}$	$\downarrow$
F	7Fh (address 127D)
	witch

#### Procedure for Node ID and Bit Rate configuration

The HI and LO hexadecimal rotary swithches set the module's Bit Rate and CAN Node ID. During the configuration, the module must be **off line** and the CAN bus must be physically disconnected.

To configure the module, follow the procedure:

- 1 Turn the Power OFF
- 2 Set the **HI** switch to "F"
- 3 Select the desired Bit Rate value by setting the LO switch following the table (e.g. "8" for 1 Mbps)
- 4 Turn the Power ON
- 5 Shift the HI switch to "E" (all the module service LEDs should flash)
- 6 Turn the Power OFF. Now configure Node ID
- 7 Set the HI and LO switches to the desired valid Node ID following the table
- 8 Turn the Power ON

Alternatively, at step 7 set the value 00h. Then, at the next Power ON, the last valid stored value will be resumed as Node ID.

The default values are: Bit Rate = 20 kbps, Node ID = 127D

#### Index 6008h - Interrupt Mask High-to-Low 8-bit

detection of a High-to-Low edge

#### Index 6005h - Global Interrupt Enable

the actual PDO transmission is performed if two initial conditions are met: the variable in Index 6005h should be "TRUE" and the PDO transmission type should be 255. In addition to the expected functions, the module provides a number of proprietary input function options. Below is an explanation of the added functions.

• Input Latch: Available for all inputs

Index 2011h – Read Input Latch contains the value of the staticised inputs.
Index 200Eh – Reset Latch commands the resetting of a single latched input on a bit basis: writing 1 to the n-th bit resets the n-th input channel. The latching function acts after the filtering and polarity settings.

• Input monostable: Available for all inputs

The input active value is maintained for a duration of time configurable with the **Index 2010h – Time Value** (16 element ARRAY, time base 5ms). The state of the inputs are kept in

Index 2012h - Read Input Wait.

#### Module specific parameters

Index 3000h - Node Address

Current Module Node ID

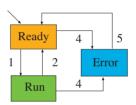
Index 3001h - Baudrate

Current Module Bit rate

#### Commands

#### Index 200Ch - Operating mode

The device has its own internal state machine. It is possible to move through this by sending appropriate values to the Index 200Ch, following the table below.



Transition	Operating mode value	Behaviour
Init	-	At Power-Up, the Device is in the "ready" state.
		Transition 1 is also executed if Index 200Ch -
		Operating Mode contains the default value 1
1	01h	Operating mode "RUN" is activated
		Return to the initialisation "ready" state.
2	00h	The transition is performed:
2		<ul> <li>following an operator's command</li> </ul>
		• after assigning a configuration parameter (2004h, 2010h)
		The "error" state is automatically assigned by the devi-
4	FFh	ce (and the operating mode value is read only) when:
		• an attempt is made to execute an unexpected command
		This value causes an exit from the "error" state, after
5	00h	the error condition is acknowledged. The only transition
		is to the "ready" state

## **Parameter configuration**

#### **Configuring the Input Channels**

The functional block diagram for the Inputs is consistent with the standard profile CiA DS401 [2].

The digital signal is first filtered (Index 6003h – Filter Constant Input 8-bit and Index 2004 - Filter Constant), then polarised (Index 6002 – Polarity Input 8-bit) and finally assigned to the variable that contains its value (Index 6000h – Read Input 8-bit). The information is now ready to be transmitted on the CAN network via the TPD01. Other entries determine the trigger condition:

Index 6006h - Interrupt Mask Any Change 8-bit:

detection of any input level change.

Index 6007h - Interrupt Mask Low-to-High 8-bit:

detection of a Low-to-High edge.

## **Emergency messages**

The module automatically sends emergency messages including error codes. The communication errors are descrided in CiA DS301 [1]. The error codes are expressed as a DEVICE SPECIFIC ERROR type of code. The codes indicating a specific condition are also inserted, following the table below:

Error code	Error
0000000000	No error -This code is generated when exiting an error conti-
	dion, to notify the end of one of the error states
0000000007	<b>Error Wrong Command</b> – An attempt to execute a command from an
	illegal state

Emergency	0	1	2	3	4	5	6	7		
	01h	FFh	21h	00h	00h	00h	00h	0yh		
Message	COB – ID = [entry 1014h] + NodelD									

#### **Parameter Store/Restore**

This module allows parameters to be saved in a non volatile memory. In order to avoid storing parameters by mistake, storage is only executed when a specific signature is written to the appropriate subindex. The signature is "save".

Similarly, the default values of parameters, according to the communication or device profile, are restored. On receipt of the correct signature in the appropriate subindex, the device restores the default parameters and then confirms the SDO transmission. The signature is "load".

The new configuration becomes active after a reset, i.e. after a "Power OFF/Power ON cycle" or an NMT "Reset Node" message.

Byte	0	1	2	3	4	5	6	7				
Store	22h	10h	10h	01h	73h	61h	76h	65h				
Parameter					S	a	٧	е				
		COB - ID = 600h + NodelD										
Restore	22h	11h 10h 01h 6Ch 6Fh 61h 6										
Parameter					I	0	a	d				
	COB - ID = 600h + NodelD											

## **SDO Messages**

The entries of a device Object Dictionary are accessed trough SDO (Service Data Object) messages. The basic SDO messages are as follows, as based on the Client – Server request and response model:

Byte	0	1 2		3	4	5	6		7	
Read Request	40h	Index		Sub-Index	Reserved					
neau nequesi	COB - ID = 600h + NodelD									
Read Response	4Fh	Inc	lex	Sub-Index		Da	ıta			
neau nesponse	COB - ID = 580h + NodelD									
Write Request	22h	Inc	lex	Sub-Index		Da	ıta			
write nequest	COB - ID = 600h + NodelD									
Write Response	60h	Inc	lex	Sub-Index		Rese	rved			
write nesponse			C	OB - ID =	580h +	NodelD				

#### **Reference documents**

List of CiA documents to which the user should refer

- [1] CiA DS301 CANopen Application Layer and Communication Profile
- [2] CiA DS401 CANopen Device Profile: for generic I/O modules

# **Accessories, Spare Parts and Warranty**

Power Supply 45W 24Vdc 2A AP-S2/AL-DR45-24 Power Supply 120W 24Vdc 5A AP-S2/AL-DR120-24 Additional Terminal Block 2x11 AP-S2/TB-211-1 Female Plug 11 Screw clamp AP-S2/SPINA-V11 Female Plug 11 Spring clamp AP-S2/SPINA-M11 RJ45 terminated cable 14cm AP-S2/LOCAL-BUS76 RJ45 terminated cable 22cm AP-S2/LOCAL-BUS152 **CAN Bus termination Adapter** AP-S2/TERM-CAN

Warranty: 3 years excluding defects due to improper use

# **Object Dictionary (with default values)**



In order to configure the module, it is necessary to connect it to a PC with the CAN interface and the superivisory software installed. The configuration can be obtained by writing the desired values to the module's variables listed in the Object Dictionary.

## **Object Dictionary structure**

ubje	Ct Di	ctionary	y structure												
Index	Sub	Object	Name	Default	Type	Acc.	MO	Index	Sub	Object	Name	Default	Type	Acc.	MO
(hex)	Index			[hex]		Attr.		(hex)	Index	,		[hex]		Attr.	
1000		VAR	Device Type	00010194	UNSIGNED32	R0	M		0Eh	VAR	Filter Constant 14	00	UNSIGNED8	RW	
1001		VAR	Error Register	00	UNSIGNED8	R0	M		0Fh	VAR	Filter Constant 15	00	UNSIGNED8	RW	
1003		ARRAY	Predefined error field	00000000	UNSIGNED32	R0	0		10h	VAR	Filter Constant 16	00	UNSIGNED8	RW	
1005		VAR	COB-ID SYNC	08000000	UNSIGNED32	RW	0	200C		VAR	Operating Mode	01	UNSIGNED8	RW	0
1006		VAR	Communication cycle period	00000000	UNSIGNED32	RW	0	200E		ARRAY	Reset Input Latch		UNSIGNED8		0
1007		VAR	Synchrounous window length	00000000	UNSIGNED32	RW	0		00h	VAR	N° of entries	02	UNSIGNED8	R0	-
1008		VAR	Manufacturer Device Name	"16LV"		const	0		01h	VAR	Reset Input Latch 1 – 8	00	UNSIGNED8	RW	
1009		VAR	Manufacturer Hardware Version	"1.00"	Vis-String	const	Õ		02h	VAR	Reset Input Latch 9 – 16	00	UNSIGNED8	RW	
100A			Manufacturer Software Version	"1.00"		const	0	2010	OZII	ARRAY	Value Time	00	UNSIGNED16		0
100C		VAR	Guard Time	0000	UNSIGNED16	RW	Õ	2010	00h	VAR	N° of entries	10	UNSIGNED8	RO	U
100D			Life Time Factor	00	UNSIGNED8	RW	0		01h	VAR	Value Time 1	0000	UNSIGNED16	RW	
1010			Store Parameters	00	UNSIGNED32	1100	Õ		02h	VAR	Value Time 2	0000	UNSIGNED16	RW	
1010	00h		Largest subindex supported	01	UNSIGNED8	R0			03h	VAR	Value Time 3	0000		RW	
	01h	VAR	Save all parameters	03	UNSIGNED32	RW			04h	VAR	Value Time 4	0000	UNSIGNED 16	RW	
1011	0111		Restore Default Parameters	00	UNSIGNED32	RW	0		05h	VAR	Value Time 5	0000		RW	
1011		ANNAI	nesture Delault Farantelers		UNSIGNED32	ΠVV	U		USII	VAN	value Time 5	0000	UNSIGNED TO	UAA	
	OOh	VAR	Largest subindey supported	Λ1	UNSIGNED8	R0			06h	VAR	Value Time 6	0000	UNSIGNED16	RW	
	00h		Largest subindex supported	01											
1014	01h	VAR	Restore all default parameters	01	UNSIGNED32	RW	0		07h	VAR	Value Time 7	0000	UNSIGNED16	RW	
1014		VAR	COB-ID EMCY	80+NodelD	UNSIGNED32	RW	0		08h	VAR		0000	UNSIGNED16	RW	
1015		VAR	Inhibit Time EMCY	0000	UNSIGNED16	RW	0		09h	VAR	Value Time 9	0000	UNSIGNED16	RW	
1017		VAR	Producer heartbeat time	0000	UNSIGNED16	RW	0		0Ah	VAR		0000	UNSIGNED16	RW	
1018	0.01		Identity Object	0.4	Identity (23h)	D0	M		0Bh	VAR	Value Time 11	0000	UNSIGNED16	RW	
	00h		Number of entries	01	UNSIGNED8	RO			0Ch	VAR		0000	UNSIGNED16	RW	
	01h	VAR	Vendor ID	000000E9	UNSIGNED32	R0			0Dh	VAR	Value Time 13	0000	UNSIGNED16	RW	
1200			Server SDO Param						0Eh	VAR		0000	UNSIGNED16	RW	
	00h	VAR	Number of entries	02	UNSIGNED8	R0	0		0Fh	VAR	Value Time 15	0000	UNSIGNED16	RW	
	01h	VAR	COB-ID Client -> Server		UNSIGNED32	R0			10h	VAR		0000	UNSIGNED16	RW	
	02h	VAR	COB-ID Server -> Client	580+NodelD	UNSIGNED32	R0		2011			Read Input Latch		UNSIGNED8		0
1800			1st Transmit PDO Comm Param		PDO CommPar (20h)		M		00h	VAR	N° of entries	02	UNSIGNED8	R0	
	00H	VAR	Largest subindex supported	05	UNSIGNED8	R0			01h	VAR	Read Input Latch 1 – 8	00	UNSIGNED8	R0	
	01h	VAR	COB-ID used		UNSIGNED32	RW			02h	VAR		00	UNSIGNED8	R0	
	02h	VAR	Transmission type	FF	UNSIGNED8	RW		2012		ARRAY	Read Input Wait		UNSIGNED8		0
	03h	VAR	Inhibit time	0000	UNSIGNED16	RW			00h	VAR	N° of entries	02	UNSIGNED8	R0	
	04h	VAR	Reseved		UNSIGNED8	RW			01h	VAR	Read Input Wait 1 – 8	00	UNSIGNED8	R0	
	05h	VAR	Event timer	0000	UNSIGNED16	RW			02h	VAR	Read Input Wait 9 – 16	00	UNSIGNED8	R0	
1801		RECORD	2nd Transmit PDO Comm Param		PDO CommPar (20h)		M	3000		VAR	Node Address	7F	UNSIGNED8	R0	0
	00h	VAR		05	UNSIGNED8	R0		3001		VAR		01	UNSIGNED8	R0	0
	01h	VAR	COB-ID used		UNSIGNED32	RW		6000			Read Input 8 – bit		UNSIGNED8		M
	02h	VAR	Transmission type	FF	UNSIGNED8	RW			00h	VAR		02	UNSIGNED8	R0	
	03h		Inhibit time	0000	UNSIGNED16	RW			01h	VAR		00	UNSIGNED8	RO	
	04h		Reseved	0000	UNSIGNED8	RW			02h	VAR		00	UNSIGNED8	RO	
	05h	VAR	Event timer	0000	UNSIGNED16	RW		6002	OZII		Polarity Input 8 – bit	00	UNSIGNED8	110	0
1A00	0011		1st Transmit PDO Mapping	0000	PDO Mapping (21h)		M	0002	00h			02	UNSIGNED8	R0	
17100		TILOUTID	1 Handille 1 Do Mapping		1 DO Mapping (211)		IVI		0011	V/ ti t	N OI CITETOS	02	ONOIGINEDO	110	
	00h	VAR	N° of mapped application obj	02	UNSIGNED8	R0			01h	VAR	Polarity 8_1	00	UNSIGNED8	RW	
	01h	VAR	DigInput8_1	60000108	UNSIGNED32	R0			02h	VAR	Polarity 8_2	00	UNSIGNED8	RW	
	02h	VAR	DigInput8_2	60000208	UNSIGNED32	R0		6003		ARRAY	Filter Constant Input 8 – bit		UNSIGNED8		0
1A01		RECORD	2 <sup>nd</sup> Transmit PDO Mapping		PDO Mapping (21h)		M		00h	VAR	N° of entries	02	UNSIGNED8	R0	
	00h	VAR	N° of mapped application obj	04	UNSIGNED8	R0			01h	VAR	FilterConst8 1	00	UNSIGNED8	RW	
	01h	VAR	Read Input Latch 1 – 8	20110108	UNSIGNED32	R0			02h	VAR	FilterConst8 2	00	UNSIGNED8	RW	
	02h	VAR	Read Input Latch 9 – 16	20110208	UNSIGNED32	RO		6005		VAR		TRUE	BOOLEAN	RW	0
	03h	VAR	Read Input Wait 1 – 8	20120108	UNSIGNED32	RO		6006			Interrupt Mask Any Change 8 - bit	THOL	UNSIGNED8		Õ
	04h	VAR	Read Input Wait 9 – 16	20120208	UNSIGNED32	RO		0000	00h	VAR	N° of entries	02	UNSIGNED8	R0	
2004	UTII		Filter Constant	20120200	UNSIGNED8	110	0		01h	VAR	InterruptAnyChange 8_1	FF	UNSIGNED8	RW	
2004	00h	VAR	N° of entries	10	UNSIGNED8	R0	U		02h	VAR		FF	UNSIGNED8	RW	
	01h	VAR	Filter Constant 1	00	UNSIGNED8	RW		6007	UZII	ARRAY	Interrupt Mask Low to High 8 - bit	11	UNSIGNED8	1100	0
		VAR		00				0007	OOh	VAR	N° of entries	02	UNSIGNED8	RO	U
	02h		Filter Constant 2		UNSIGNED8	RW			00h			02			
	03h		Filter Constant 3	00	UNSIGNED8	RW			01h		InterruptLowToHigh 8_1	00	UNSIGNED8	RW	
	04h		Filter Constant 4	00	UNSIGNED8	RW		6000	UZII	VAR	InterruptLowToHigh 8_2	00	UNSIGNED8	RW	0
	05h	VAR	Filter Constant 5	00	UNSIGNED8	RW		6008	005	AKKAY	Interrupt Mask High to Low 8 - bit	00	UNSIGNED8	DO	0
	06h		Filter Constant 6	00	UNSIGNED8	RW			00h			02	UNSIGNED8	RO	
	07h	VAR	Filter Constant 7	00	UNSIGNED8	RW			01h	VAR		00	UNSIGNED8	RW	
	08h	VAR	Filter Constant 8	00	UNSIGNED8	RW			U2h	VAR	InterruptHighToLow8_2	00	UNSIGNED8	RW	
	09h	VAR	Filter Constant 9	00	UNSIGNED8	RW									
	0Ah		Filter Constant 10	00	UNSIGNED8	RW									
	0Bh	VAR	Filter Constant 11	00	UNSIGNED8	RW									
	0Ch		Filter Constant 12	00	UNSIGNED8	RW									
	0Dh	VAR	Filter Constant 13	00	UNSIGNED8	RW									